

MOTORS

Technical Information & User Manual

Orbital Motors with Speed Sensors



together in motion

White is a leading global provider of motor and steering solutions that power the evolution of mobile and industrial applications around the world.



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Safety precautions

Always consider safety precautions before beginning a service procedure. Protect yourself and others from injury. Take the following general precautions whenever servicing a hydraulic system.

Unintended machine movement



Warning:

Unintended movement of the machine or mechanism may cause injury to the technician or bystanders. To prevent unintended movement, secure the machine or disable / disconnect the mechanism while servicing.

Flammable cleaning solvents



Warning:

Some cleaning solvents are flammable. To eliminate the risk of fire, do not use cleaning solvents in an area where a source of ignition may be present.

Fluid under pressure



Warning:

Escaping hydraulic fluid under pressure can have sufficient force to penetrate your skin causing serious injury and/or infection. This fluid may also be hot enough to cause burns. Use caution when dealing with hydraulic fluid under pressure. Relieve pressure in the system before removing hoses, fittings, gauges or components. Never use your hand or any other body part to check for leaks in a pressurized line. Seek medical attention immediately if you are cut by hydraulic fluid.

Personal safety



Warning:

Protect yourself from injury. Use proper safety equipment, including safety glasses, at all times.

Chapter 1

Motor with speed sensor

Topics:

- *LSHT motor with disc valve*
- *Technical data for OMM EM*
- *Dimensions*

LSHT motor with disc valve

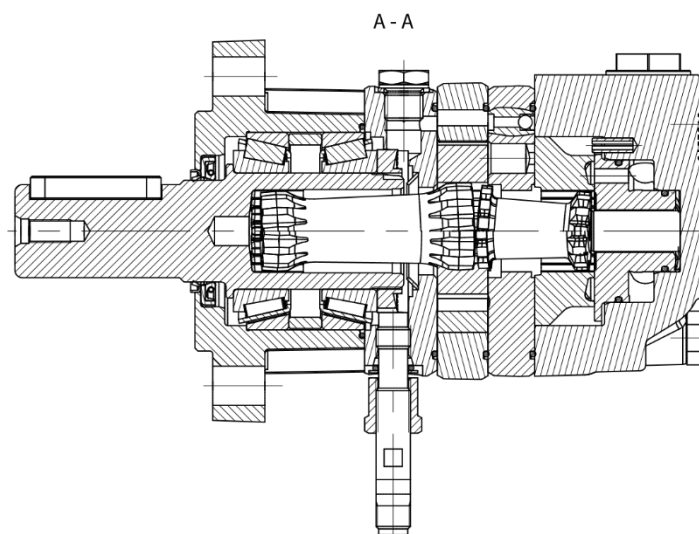


Figure 1 LSHT motor with disc valve

Technical data for OMM EM

Permissible shaft load

Permissible radial shaft load must be reduced by 30% compared to motors without speed sensor.

Dimensions

OMM EM

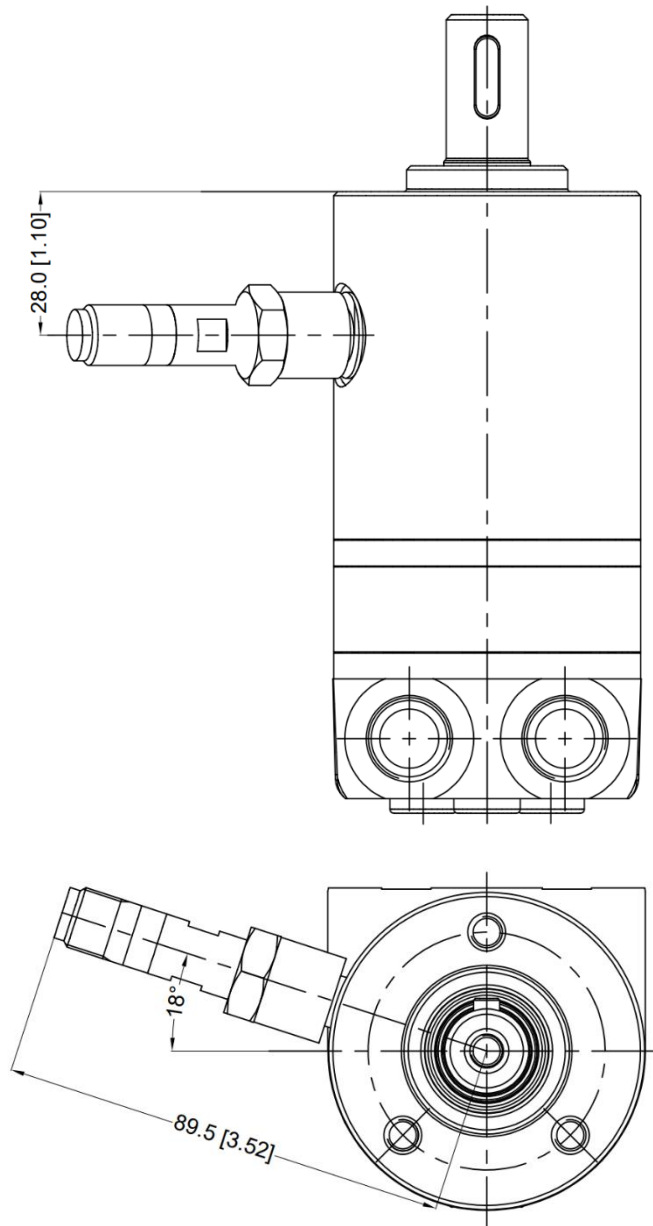


Figure 2 OMM EM

OMP EM

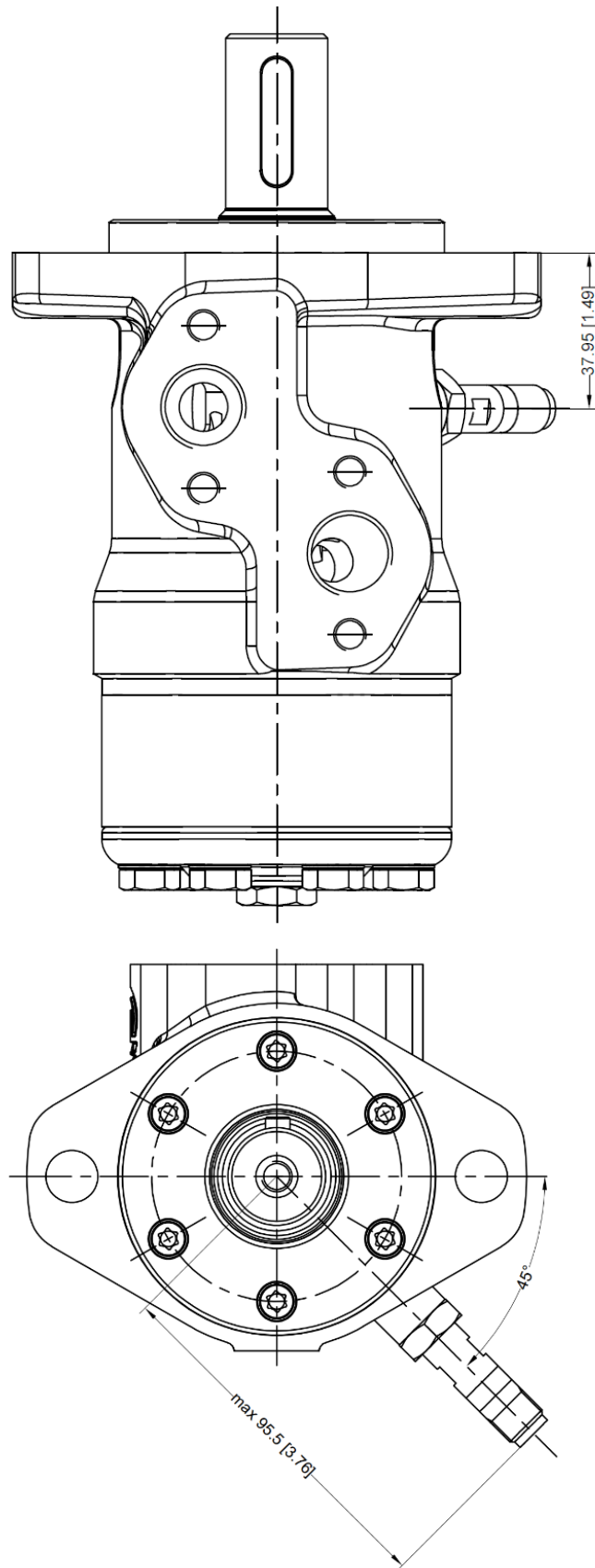


Figure 3 OMP EM

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OMR EM

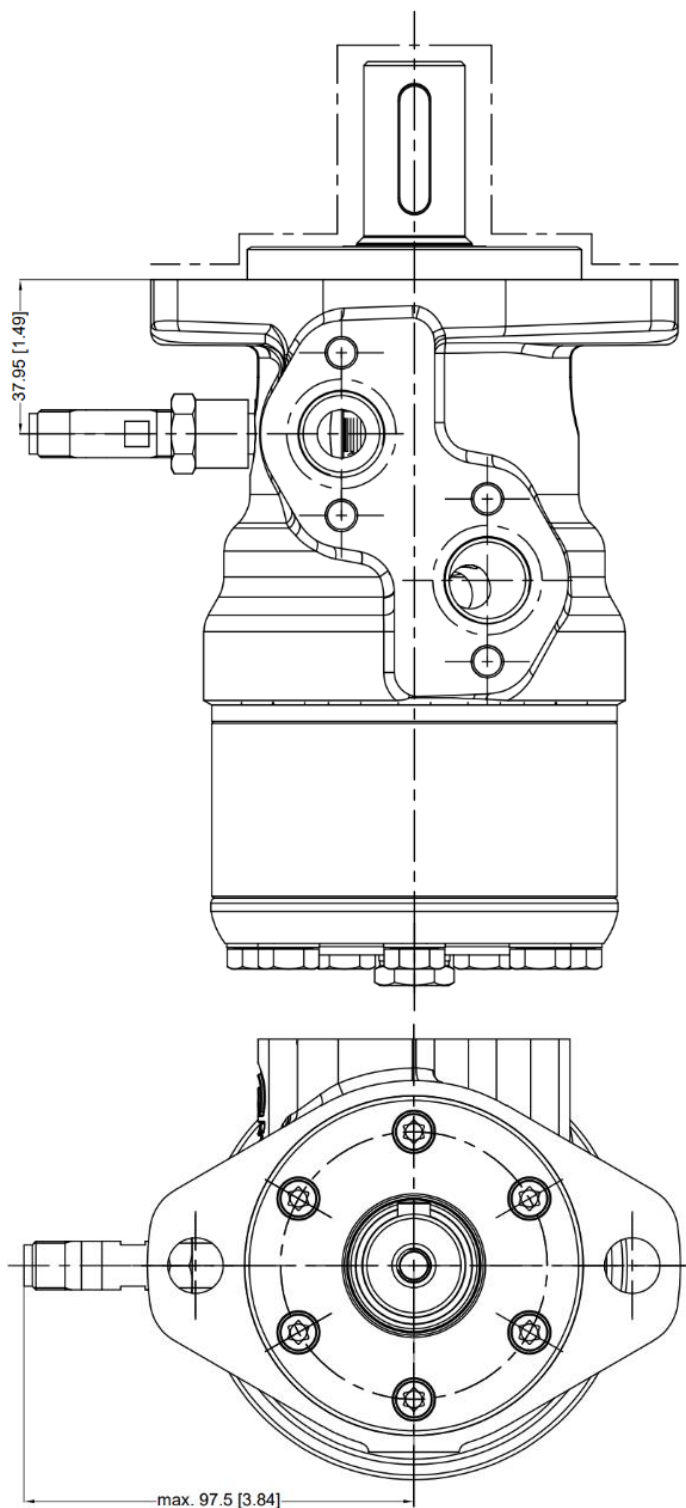


Figure 4 OMR EM

OMS EM

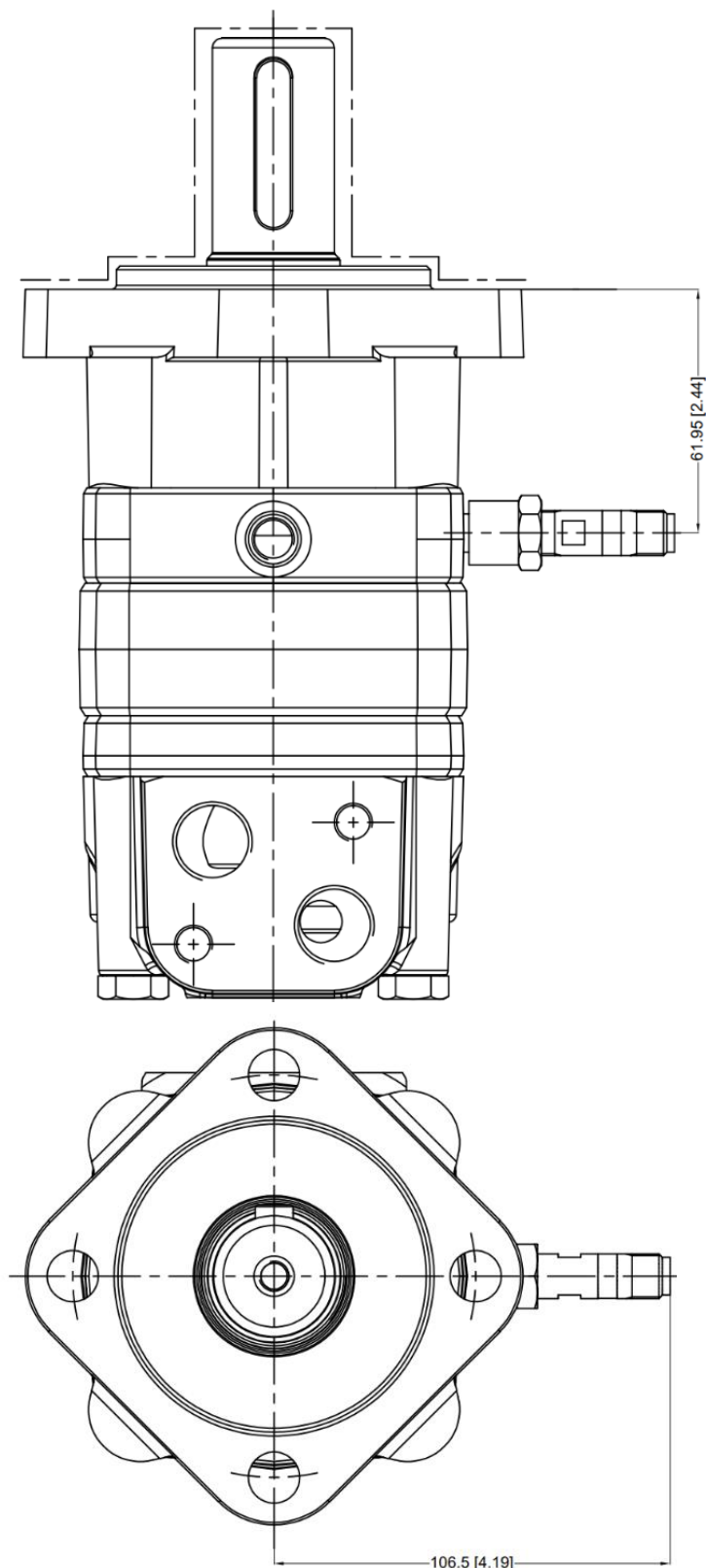


Figure 5 OMS EM

OMSW EM

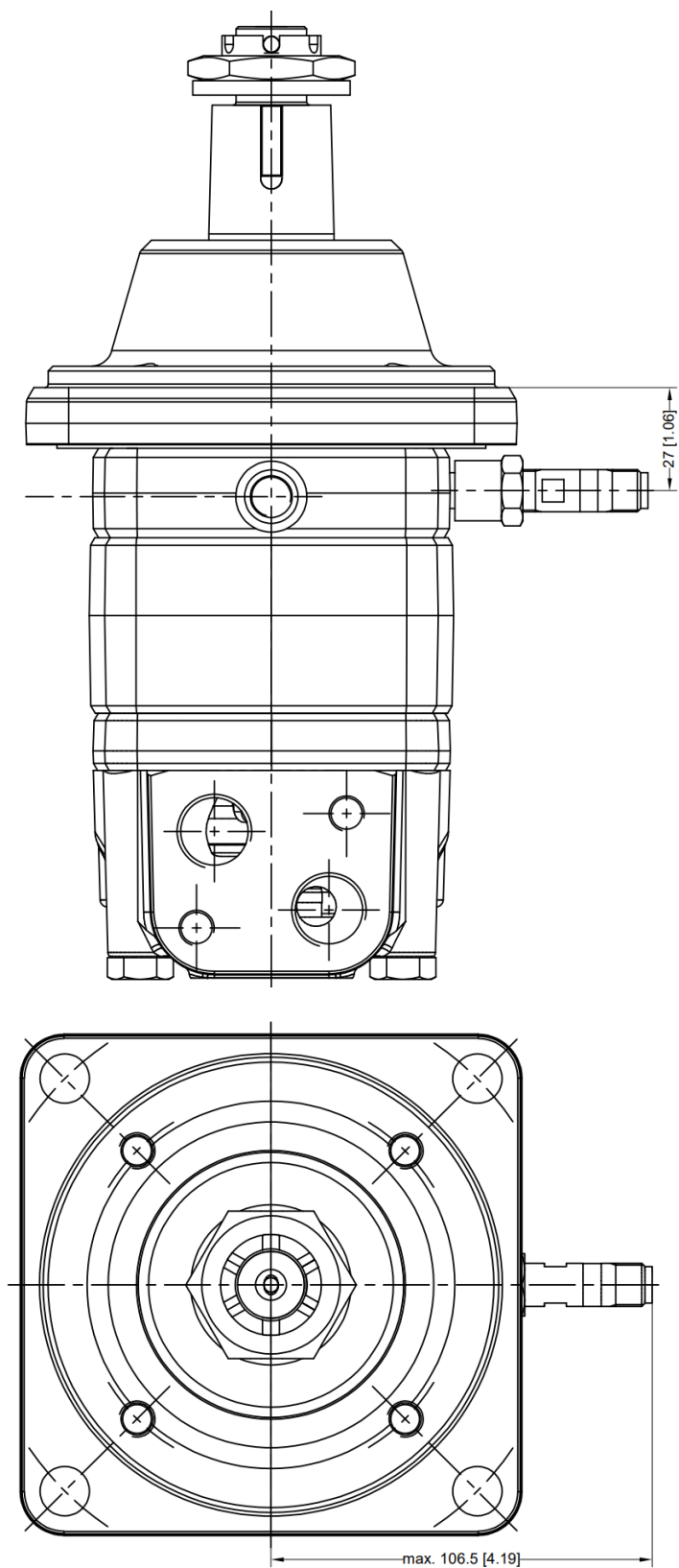


Figure 6 OMSW EM

Chapter 2

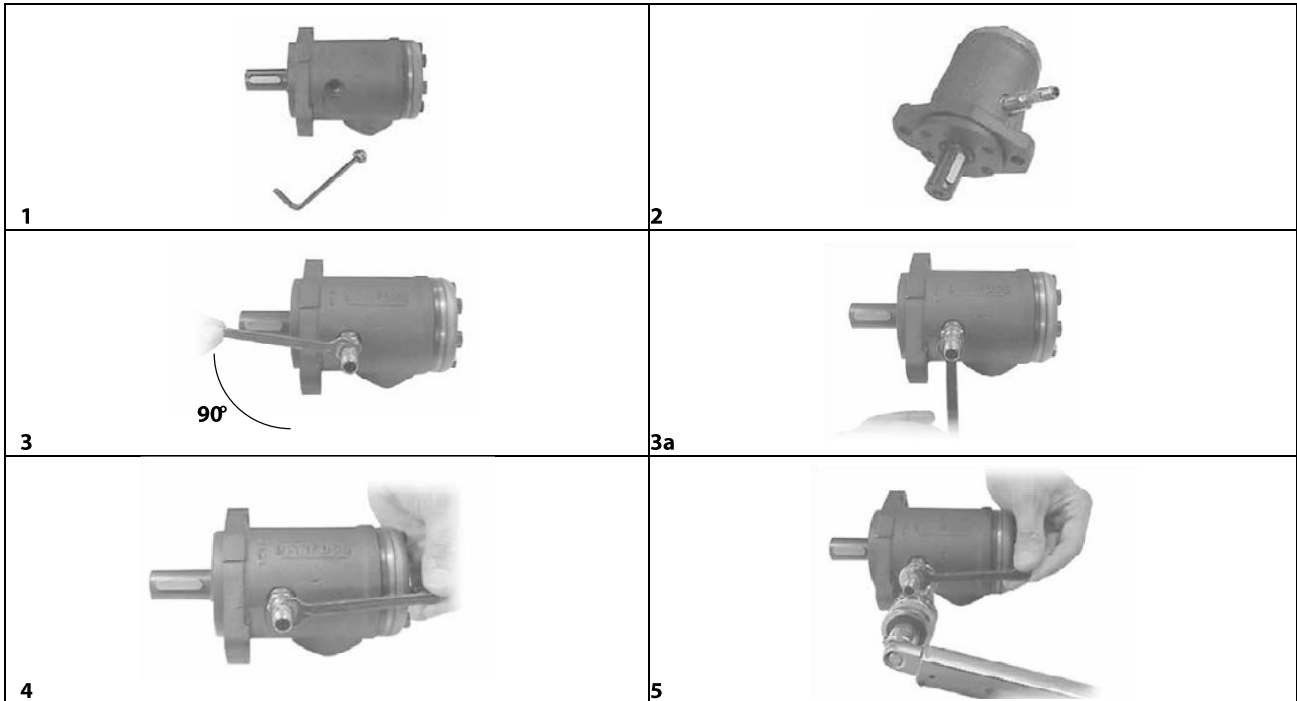
Installation guide

Topics:

- [Installation Guide](#)
- [Testing](#)

Installation Guide

Motor with speed sensor OMM EM, OMP EM, OMR EM, OMS EM, OMSW EM



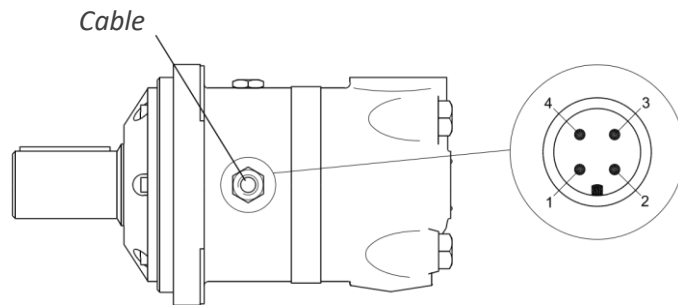
1. Remove the plug and washer from the motor (6 mm Allen key).
2. Without tools screw in the sensor till it makes contact with the shaft/nut of the motor.
3. Turn 1/4 revolution back again (90°) as shown on *photo 3a*.
4. Turn back further until the 10 mm flats of the sensor are aligned with the longitudinal axis of the motor. Tolerance $\pm 5^\circ$.
5. Keep the sensor in this position while tightening the compression nut to the prescribed torque of 15-20 Nm.

To make the sensor work, be sure to carry out the steps 2 – 5 correctly and in the right order of succession.

Connection

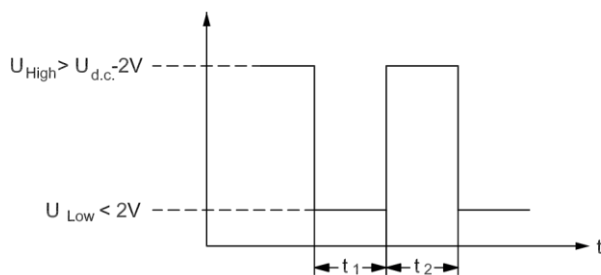
Attention: Don't turn the socket

Connection: Binder series 713



Pin	Conductor	Designation	Specification
1	Brown	Supply	11 - 30 V ₌₌₌
2	White	Not connected	
3	Blue	Supply	0V ₌₌₌
4	Black	Signal	See below

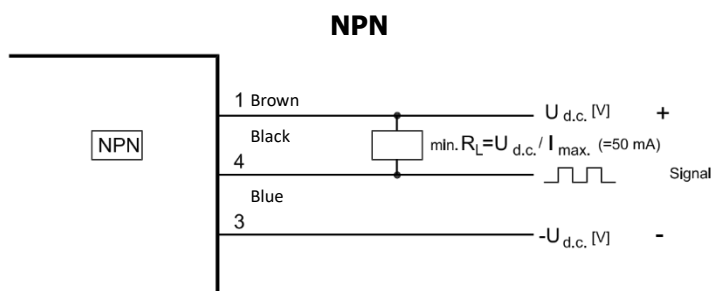
Speed signal



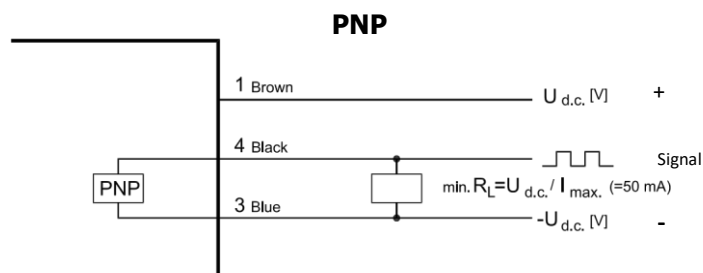
$$t_1 = t_2 \pm 10\%$$

Motor type	OMM EM	OMP EM	OMR EM	OMS EM	OMSW EM
Pulses per rev.	22	35	35	55	55
Load	$I_{\max} = 50 \text{ mA}$				

Connection diagram



Connection diagram



Testing

Measuring - duty cycles

1. Mount the sensor in motor in accordance with **DOC00031192 (NPN)** or **DOC00031191 (PNP)** and place the motor in the test panel.
2. Connect power supply and multimeter (with Hz measuring option) as described in the diagram.
3. Set rotary switch of multimeter on V and activate Hz pushbutton twice (for % measuring).
4. With an oil flow to the motor sufficient to ensure even revolution with a warm motor.

Measure the following duty cycles:

Motor type	Duty cycle (%)
OMM EM	50 +/- 10
OMP EM	55 +/- 5
OMR EM	55 +/- 5
OMS/OMSW EM	55 +/- 5

Measuring - revolutions per minute

Measure also the frequency (F_r) with the multimeter and calculate the revolutions per minute and compare it with RPM-counter on the test panel.

$$RPM = \frac{F_r * 60}{PPR}$$

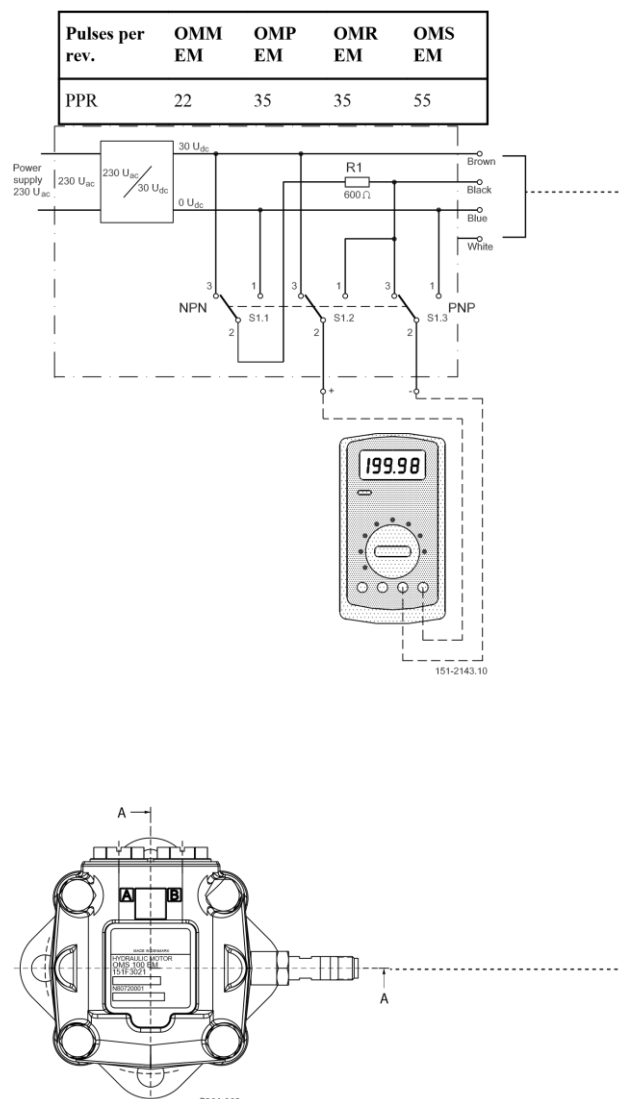


Figure 7 Resolution



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